Ground LiDAR fuel measurements of the Prescribed Fire Combustion and Atmospheric Dynamics Research Experiment

Eric Rowell, Erik Apland and Carl Seielstad



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Overview:

- Describe the Terrestrial Laser Scanning Field Mission.
- Present Processing Methods and Data Produced.
- Discuss Fuel Modeling, Mapping, and Change Detection.
- Examine Preliminary Results.

Purpose: Science and Applications

- To map fuel properties at fine grain for validating fire models (field fuels data, photos/images)
- To better understand relationships between vegetation structure and fire behavior and effects (thermal camera and flux package data)
- To decompose the relative contributions of fuels and wind on fire behavior at fine grain (wind, thermal camera, video, airborne thermal data)
- To study performance of laser scanning for characterizing vegetation properties of landscapes through comparison of airborne and terrestrial lidar *(airborne laser altimetry data)*

Instrument Specifications:



- Optech ILRIS 3₆D ER Scanner
- ✤ 1535 nm wavelength laser
- ✤ 10 kHz scan speed; scans in 40° blocks
- ✤ 13 mm spot at 5 m; 29 mm spot at 100 m
- ✤ Range of ~1700 m at 80% reflectivity
- Spot spacing to 1 mm.
- Records x,y,z,i
- SLR camera collects RGB images.



Scanning Protocols:



- ✤ Scan from boomlift 16-27 m AGL.
- Remote operation of laser system.
- Reflective targets set at clip-plot and at unit corners.
- ✤ 95 good scans; 15 bad scans
- ✤ Average 27 minutes per scan- 49 hours
- ✤ 60 hours of instrument set-up.



Scanning Protocols:





- Scanned pre- and post-fire.
- Spot spacing 36mm at 100m for large units (S-Blocks)
- Spot spacing 6mm at 25m for small units (Highly Instrumented Plots (HIPS))
- ✤ Laser spot size at 100m: 29 mm
- ✤ Laser spot size at 25m: 18mm

Data Acquisition: S-Blocks



Data Acquisition: S-Blocks



Data Acquisition: HIPS



Data Acquisition: HIPS



L2FH2





Methods: Parsing, Rotating, Merging

Parsing

1. Laser data are exported to .pif and .xyz formats

Aligning

- 1. In Polyworks IMAlign adjacent scans are combined using tie points, manual, and automated align.
- 2. Alignment rotation matrices exported.

Rotating and Merging

- .xyz data are rotated using matrices in IDL-scripted TLS Processor 1.2beta
- 2. Aligned data are merged into a single dataset using IDL-scripted TLS Processor 1.2beta.

Generate Bare Earth Surface

- 1. Convert TLS pointcloud to LAS format.
- 2. Use LAStools LASground algorithm, with settings for ground area, de-spiking height and ground surface variability for TIN creation.
- Normalize heights of vegetation points to heights above ground surface (CHM) using LASheight.

Data Density & Grain Size



The Bare Earth DEM



Methods: Derivation of Metrics

Vertical Height Metrics Percentile Min, Max Mean, Median, Mode Variance, Std Deviation Inflection Ratio above/below	<u>Horizontal 'Cover' Metrics</u> Laser Gap Fraction Return Density Convex Hull (surface area)	Reflectance Metrics Laser Intensity Red, Green, Blue
	Volume Metrics Proportion Filled Volume Convex Hull (volume)	

Height Metrics



Cover Metrics: Laser Gap Fraction



Laser Gap Fraction (L2GH3)

Modeling: Biomass



Fuel Class	R	R ²	Std Error
Total biomass (peak)	0.96	0.93	0.59
Biomass exc. litter (peak)	0.97	0.93	0.59
Total biomass (inflection)	0.87	0.76	1.08

Fuel Class	R	R ²	Std Error
Total Biomass (peak)	0.89	0.79	0.44
Biomass exc. Litter (peak)	0.83	0.69	0.54
Biomass exc. woody (inflection)	0.88	0.77	0.45

Mapping:



		Reference		
	Shrub	Grass/Forb	Bare	Row Total
Shrub	22	2	0	24
Grass/Forb	2	28	8	38
Bare	0	5	13	18
Column Total	24	35	21	80

- 10 Class ISODATA using height and gap metrics.
- ✤ Merged to 3 classes.
- Overall per-pixel accuracy: 79%
- Shrub per pixel accuracy: 91%
- Some confusion between Grass and Bare.
- Little differentiation between Grass and Forb.

Mapping:



Intensity/Reflectance Metrics





RGB Mapped to Point Cloud (L2GH3)

Laser Reflectance (L2GH3)

Summary:

- Comprehensive TLS datasets were collected pre- and post-fire for six 2 ha burn blocks and nine 0.04 ha highly instrumented plots, coincident with many field/clip plots.
- A processing stream was developed to merge and project many scans, and to classify and normalize points.
- A suite of gridded height, cover, and intensity metrics is being generated for each dataset.
- Fuel height is the native derivative of the data. Modeling fuel mass using height and convex hull is promising.
- Shrub, grass/forb, and bare ground can be classified effectively on at least three plots.

Tentative Data Delivery:

- Merged, unclassified laser point clouds in UTM projection (xyzi) for each S-Block and HIPS pre- and post- fire.
- ✤ Bare earth DEMs.
- Grids at 1m² (S-blocks), 0.25m² (HIPS) for some fraction of laser metrics.
- * Grids of Fuel Metrics- pending outcomes of analyses.
- We are still soliciting input on grain size, metrics, and data formats.